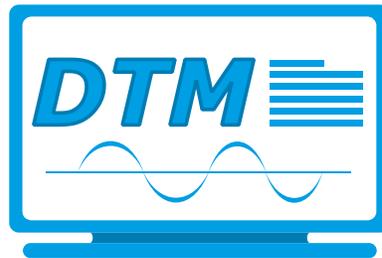


KLAY-INSTRUMENTS

INSTRUCTION MANUAL

DTM - HART SERIES 9000 and 9000-SAN



For optimal use read the recommendations and warnings in this manual, these instructions should be studied carefully.

Manufactured by:

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1. INTRODUCTION

This instruction manual is a guide for installing and using the intelligent pressure and level transmitter Series 9000 and 9000-SAN HART. This DTM is developed to make configuration changes of the Series 4000 transmitters easy. This DTM can be used with almost every FDT-container.

2. INSTALLATION

To install the Klay DTM Series 9000 on your system, you have to download the installation file. This file can be downloaded from the Klay Instruments website: www.klay-instruments.com under section downloads.

To start the installation always extract **Klay Series 9000 HART_1.0.1.zip**.
Select **Klay Series 9000 HART.exe** * (You must have administrator rights, do not use the .msi file)

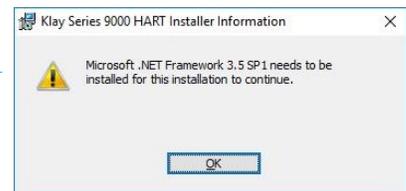
**Minimal software requirements: Windows 7 (32 or 64 bit) or higher, for older versions please contact Klay Instruments.*



2.1 .NET Framework 3.5

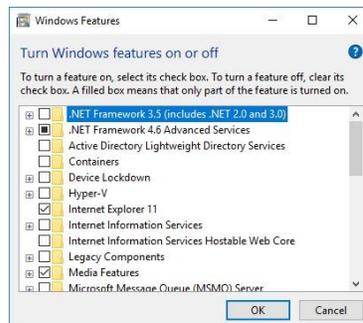
The Klay DTM requires .NET Framework 3.5 from Microsoft.
If the framework is already installed the setup will continue.

When the framework is not installed the following message appear:



Windows 7 users can download the .NET Framework package from the following location: <https://www.microsoft.com/nl-nl/download/details.aspx?id=21>

Windows 10 and 8 users can enable the .NET Framework by selecting the start menu and type windows features in the search box.
The following window appears and the .NET Framework 3.5 can be enabled.

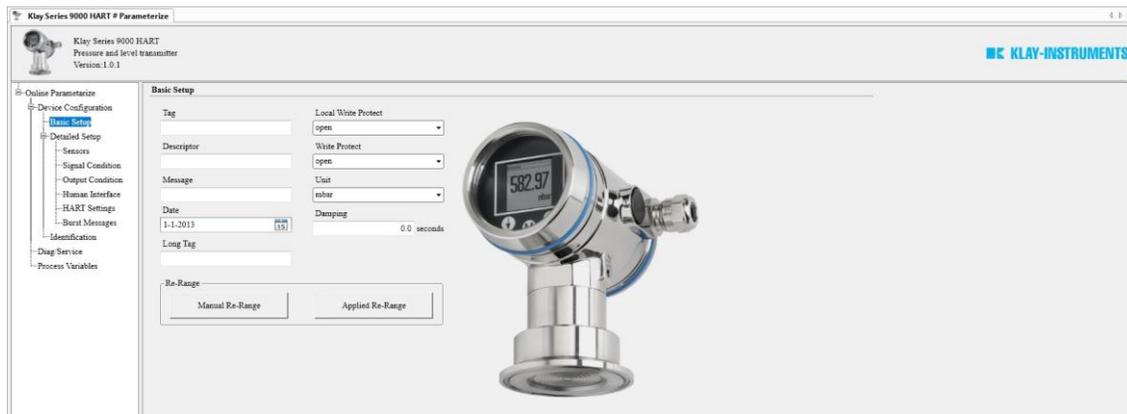


3. DTM

The following pages describes the DTM configuration.

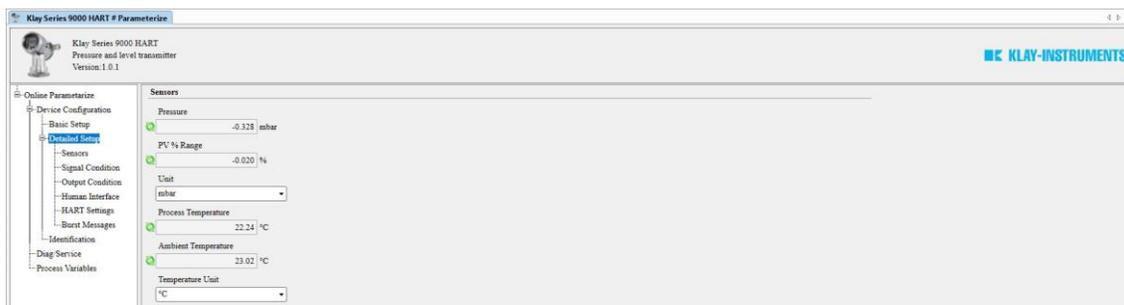
3.1 BASIC SETUP

In this menu basic data of the transmitter can be configured. Information like Tag Number, Descriptor and others can be entered in the text fields. In this menu it is possible to change the span (LRV and URV) of the transmitter without test pressure with the option **Manual Re-Range**, follow the displayed instructions. With the option **Applied Re-Range** the span can be changed with a test pressure, follow the displayed instructions. Damping can be adjusted between 0 and 25 seconds. With the option **Local Write Protect**, protection against local adjustment on the transmitter can be set. With the option **Write Protect**, protection against adjustment by HART® can be set. The engineering unit of the pressure and temperature can be changed in this menu.



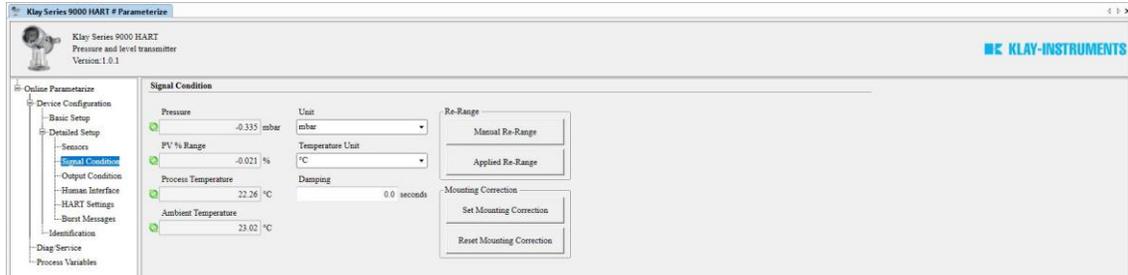
3.2 DETAILED SETUP

This menu contains data like the actual pressure, sensor and ambient temperature, these values are refreshed every 10 seconds. The engineering unit of the pressure and temperature can be changed.



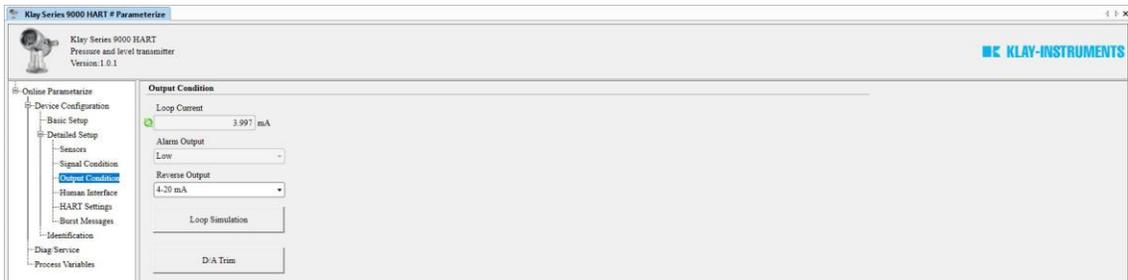
3.3 SIGNAL CONDITION

This menu contains data like the actual pressure, sensor and ambient temperature. These values are refreshed every 10 seconds. The engineering unit of the pressure and temperature can be changed. In this menu it is also possible to change the span (LRV and URV) of the transmitter without test pressure with the option **Manual Re-Range**, follow the displayed instructions. With the option **Applied Re-Range** the span can be changed with a test pressure, follow the displayed instructions. The mounting position effect of the transmitter can be neutralized with the option **Set Mounting Correction** or reset to factory default with the option **Reset Mounting Correction**. Damping can be adjusted between 0 and 25 seconds.



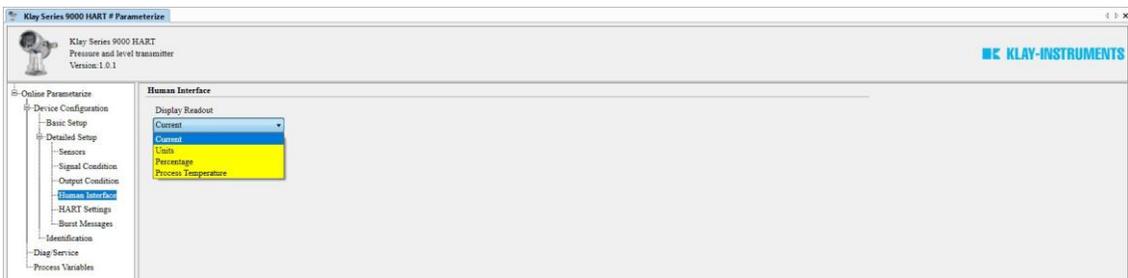
3.4 OUTPUT CONDITION

This menu contains the actual loop current of the transmitter. The output of the transmitter can be configured into **4-20 mA** or **20-4 mA**. With the option **Loop Simulation** a current can be simulated. Three options are available: **4 mA**, **20 mA** and **Other**. With **Other** a manual value between 4 and 20 can be chosen. To end the simulation choose **End** after selecting Loop Simulation. When necessary the output can be trimmed with D/A Trim.



3.5 HUMAN INTERFACE

In the menu Human Interface a Readout option can be configured. **Readout:** Current, Unit, Percentage, and Process Temperature.



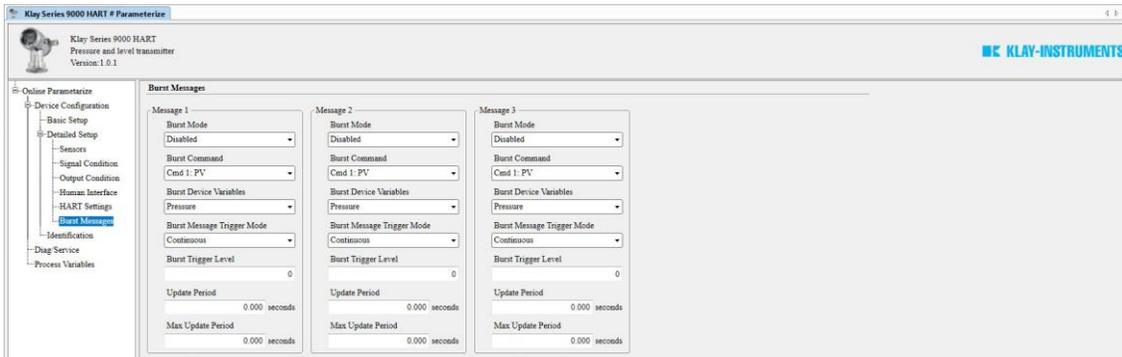
3.6 HART SETTINGS

In this menu several HART® options can be configured. When using HART® devices in a multi-drop configuration where more than one device is in the loop, each device must be set to a different polling address. The polling address for identification to the Host device can be filled in. With the option Set Clock Time the real time clock can be set in the Field device.



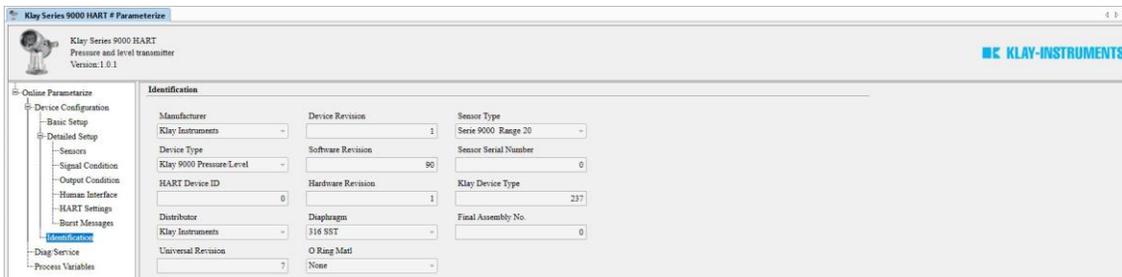
3.7 BURST MESSAGES

In this menu the transmitter can be configured for Burst mode. This will enable continuously broadcasting standard HART® reply messages. 3 (different) types of Burst messages can be configured. For a detailed explanation of the burst command, variables and message modes, details can be found in the instruction manual of the Series 9000. Depending on the Master one message will continuously be broadcasted to the Master device (when enabled).



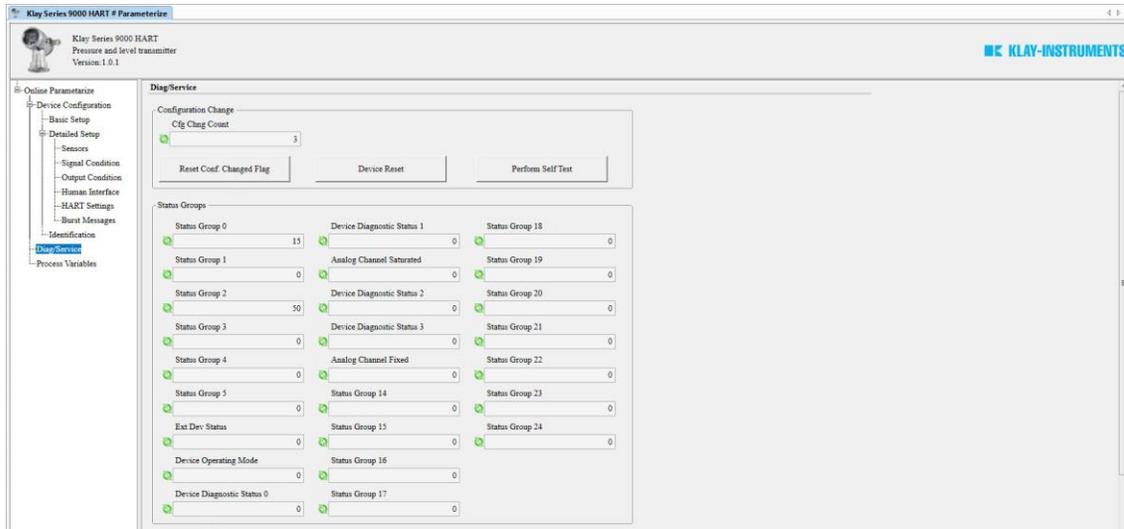
3.8 IDENTIFICATION

This menu shows data about the transmitter. This data is read-only and cannot be changed. The data contains information about: The manufacturer, type of transmitter, serial number, revision and others.



3.9 DIAGNOSTICS AND SERVICE

Diagnostic and service contains several status bits. These flags and status bits are used by the master device. **Cfg Chng Count** displays the number configured changes. With button **Device Reset**, the transmitter will restart. With button **Perform Self-Test**, the transmitter performs a hardware self-test, follow the displayed instructions.



3.10 PROCESS VARIABLES

In this menu the actual readings of the transmitter are displayed. The actual readings are refreshed every 10 seconds. The engineering unit of the pressure and temperature can be changed in this menu.

